You're at a party. . .

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What I would answer. . .

- Find a plan that brings about a desired goal/action/state
- Given:
  - knowledge of how the world works. . .
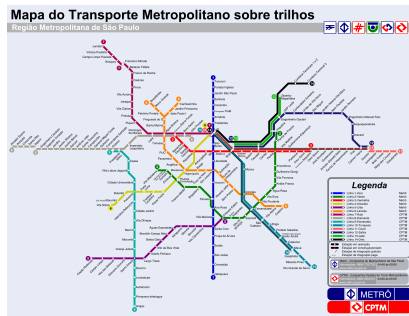 - and how our actions change it

Tourists in São Paulo

- **Goal:** eat at a Churrascaria
- **Knowledge:**
  - metric map
  - topological map
  - semantic map
  - transportation modes
  - time estimates
  - relative locations
  - retaurant taxonomy
  - commonsense knowledge
  - . . .

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Mapa do Transporte Metropolitano sobre trilhos
Região Metropolitana de São Paulo

Was this a planning problem?

- Causal knowledge
    - PDDL, HTN/STN, State variables, . . .
- Temporal knowledge
    - LTL, TCSP/STP, DTP, Allen's Intervals, INDU, . . .
- Resource knowledge
    - Consumable, reusable, multi-capacity, binary, . . .
- Spatial knowledge
    - RCC, Cardinal Relations, Point Algebras, . . .
- Ontologies, commonsense knowledge
    - OWL-DL, OpenMind (Indoor Robot Commonsense), OpenCyc, . . .
- . . .

If the answer is "Yes"...

- ... let's remember that we *have* inference procedures / solvers for many of these sub-problems
- ... and that integration methodologies which leverage these capabilities *have* been developed
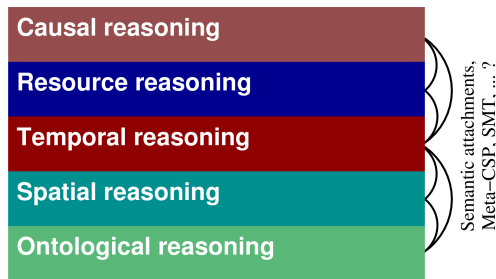
Not just an academic curiosity. . .

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RCC, AIA, LTL, OWL, HTN, PDDL, ...

. . . just ask Tony Cohn! (and go see his invited talk tomorrow)